

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings of claims in the application:

**Listing of Claims:**

1-2. (Canceled)

3. (Currently amended) A defect inspection method comprising the steps of:  
applying a focused electron beam onto a sample and conducting scanning;  
detecting secondary electrons generated from an inspection subject region of said  
sample at the focused electron beam applying step by using detectors installed in a plurality of  
directions, thereby obtaining external appearance images of the inspection subject region of said  
sample picked up from the plurality of directions;  
picking up images of a comparison subject region designed so as to originally  
have an external appearance identical with that of the inspection subject region of said sample  
from a plurality of directions identical with those of the inspection subject region, thereby  
obtaining external appearance images of the comparison subject region picked up from the  
plurality of directions;  
correcting mis-registrations between the external appearance images of the  
inspection subject region of said sample picked up from the plurality of directions and the  
external appearance images of the comparison subject region picked up from the plurality of  
directions that respectively correspond to the external appearance images of the inspection  
subject region picked up from the plurality of directions; and  
detecting defects of the inspection subject region by using the external appearance  
images of the inspection subject region of said sample picked up from the plurality of directions  
and the external appearance images of the comparison subject region picked up from the  
plurality of directions corrected in mis-registrations~~The defect inspection method according to~~  
~~claim 1,~~ wherein the step of correcting the mis-registrations comprises the substeps of:

22 mixing two perspective images obtained by picking up an image of the inspection  
23 subject region of said sample from each of two opposed directions with a non-directional  
24 electron image, thereby synthesizing a first mixed image;

25 mixing two perspective images obtained by picking up an image of the  
26 comparison subject region of said sample from each of the two opposed directions with a non-  
27 directional electron image, thereby synthesizing a second mixed image; and

28 comparing the first mixed image with the second mixed image, thereby obtaining  
29 mis-registration quantities respectively between the two perspective images and the non-  
30 directional electron image of the inspection subject region of said sample and the two perspective  
31 images and the non-directional electron image of the comparison subject region.

1 4. (Original) The defect inspection method according to claim 3, wherein  
2 the step of synthesizing the first mixed image comprises the substep of using  
3 information of a difference image between two perspective images obtained by picking up an  
4 image of the inspection subject region of said sample from each of two opposed directions, and  
5 the step of synthesizing the second mixed image comprises the substep of using  
6 information of a difference image between two perspective images obtained by picking up an  
7 image of the comparison subject region from each of two opposed directions.

5. (Canceled)

1 6. (Currently amended) A defect inspection method comprising the steps of:  
2 applying a focused electron beam onto a sample and conducting scanning;  
3 detecting secondary electrons generated from an inspection subject region of said  
4 sample at the focused electron beam applying step by using detectors installed in a plurality of  
5 directions, thereby obtaining external appearance images of the inspection subject region of said  
6 sample picked up from the plurality of directions;  
7 picking up images of a comparison subject region designed so as to originally  
8 have an external appearance identical with that of the inspection subject region of said sample  
9 from a plurality of directions identical with those of the inspection subject region, thereby

10 obtaining external appearance images of the comparison subject region picked up from the  
11 plurality of directions;

12 correcting mis-registrations between the external appearance images of the  
13 inspection subject region of said sample picked up from the plurality of directions and the  
14 external appearance images of the comparison subject region picked up from the plurality of  
15 directions that respectively correspond to the external appearance images of the inspection  
16 subject region picked up from the plurality of directions; and

17 detecting defects of the inspection subject region by using the external appearance  
18 images of the inspection subject region of said sample picked up from the plurality of directions  
19 and the external appearance images of the comparison subject region picked up from the  
20 plurality of directions corrected in mis-registrations~~The defect inspection method according to~~  
21 ~~claim 1~~, wherein the step of detecting defects of the inspection subject region comprises the  
22 substeps of:

23 using information of a difference image and a sum image of two perspective  
24 images obtained by picking up an image of the inspection subject region of said sample from  
25 each of two opposed directions; and

26 using information of a difference image and a sum image of two perspective  
27 images obtained by picking up an image of the comparison subject region from each of two  
28 opposed directions.

1 7. (Currently amended) A defect inspection method comprising the steps of:  
2 applying a focused electron beam onto a sample and conducting scanning;  
3 detecting secondary electrons generated from an inspection subject region of said  
4 sample at the focused electron beam applying step by using detectors installed in a plurality of  
5 directions, thereby obtaining external appearance images of the inspection subject region of said  
6 sample picked up from the plurality of directions;

7 picking up images of a comparison subject region designed so as to originally  
8 have an external appearance identical with that of the inspection subject region of said sample  
9 from a plurality of directions identical with those of the inspection subject region, thereby

10 obtaining external appearance images of the comparison subject region picked up from the  
11 plurality of directions;

12 correcting mis-registrations between the external appearance images of the  
13 inspection subject region of said sample picked up from the plurality of directions and the  
14 external appearance images of the comparison subject region picked up from the plurality of  
15 directions that respectively correspond to the external appearance images of the inspection  
16 subject region picked up from the plurality of directions; and

17 detecting defects of the inspection subject region by using the external appearance  
18 images of the inspection subject region of said sample picked up from the plurality of directions  
19 and the external appearance images of the comparison subject region picked up from the  
20 plurality of directions corrected in mis-registrations~~The defect inspection method according to~~  
21 ~~claim 1~~, wherein the step of detecting defects of the inspection subject region comprises the  
22 substeps of:

23 obtaining a difference image between a non-directional electron image obtained  
24 by picking up an image of the inspection subject region of said sample and a non-directional  
25 electron image obtained by picking up an image of the comparison subject region, by using local  
26 perturbation; and

27 detecting defects of the inspection subject region by using information of the  
28 difference image obtained by using the local perturbation.

1 8. (Currently amended) A defect inspection method according to claim  
2 ~~[[1]]~~6, further comprising the step of classifying the detected defects by processing the defect  
3 region.

1 9. (Original) A defect inspection method comprising the steps of:  
2 applying a focused electron beam onto a sample and conducting two-dimensional  
3 scanning on an inspection subject region;  
4 detecting secondary electrons generated from an inspection subject region of said  
5 sample at the focused electron beam applying step by using a plurality of detectors, thereby

6 obtaining a plurality of external appearance images of the inspection subject region of said  
7 sample;

8 picking up images of a comparison subject region designed so as to originally  
9 have an external appearance identical with that of the inspection subject region of said sample by  
10 using said plurality of detectors, thereby obtaining a plurality of external appearance images of  
11 the comparison subject region;

12 combining the plurality of external appearance images of the inspection subject  
13 region of said sample to form a first synthetic image and combining the plurality of external  
14 appearance images of the comparison subject region to form a second synthetic image;

15 obtaining a mis-registration quantity between the formed first synthetic image and  
16 the formed second synthetic image;

17 correcting mis-registrations between the plurality of external appearance images  
18 of the inspection subject region of said sample and the plurality of external appearance images of  
19 the comparison subject region that respectively correspond to the plurality of external appearance  
20 images of the inspection subject region, based on the obtained mis-registration quantity; and

21 detecting defects of the inspection subject region by using the plurality of external  
22 appearance images of the inspection subject region of said sample and the plurality of external  
23 appearance images of the comparison subject region corrected in the mis-registrations.

1 10. (Original) The defect inspection method according to claim 9, wherein at  
2 the step of obtaining external appearance images of the inspection subject region of said sample,  
3 the plurality of external appearance images of the inspection subject region of said  
4 sample comprise two perspective images obtained by picking up an image of the inspection  
5 subject region of said sample from each of two opposed directions, and a non-directional  
6 electron image, and

7 the plurality of external appearance images of the comparison subject region  
8 comprise two perspective images obtained by picking up an image of the comparison subject  
9 region from each of two opposed directions, and a non-directional electron image.

1           11. (Original) The defect inspection method according to claim 9, wherein the  
2 step of correcting the mis-registrations comprises the substeps of:

3                 mixing two perspective images obtained by picking up an image of the inspection  
4 subject region of said sample from each of two opposed directions with a non-directional  
5 electron image, thereby synthesizing a first mixed image;

6                 mixing two perspective images obtained by picking up an image of the  
7 comparison subject region of said sample from each of the two opposed directions with a non-  
8 directional electron image, thereby synthesizing a second mixed image; and

9                 comparing the first mixed image with the second mixed image, thereby obtaining  
10 mis-registration quantities respectively between the two perspective images and the non-  
11 directional electron image of the inspection subject region of said sample and the two perspective  
12 images and the non-directional electron image of the comparison subject region.

12-14. (Canceled)

1           15. (Currently amended) A defect inspection method comprising the steps of:  
2 applying a focused electron beam onto a sample and conducting scanning;

3 picking up images of an inspection subject region of said sample from a plurality  
4 of directions, thereby obtaining a plurality of external appearance images of the inspection  
5 subject region;

6 picking up images of a comparison subject region designed so as to originally  
7 have an external appearance identical with that of the inspection subject region of said sample  
8 from a plurality of directions, thereby obtaining a plurality of external appearance images of the  
9 comparison subject region;

10 detecting defects of said sample by using the plurality of external appearance  
11 images of the inspection subject region and the plurality of external appearance images of the  
12 comparison subject region;

13 classifying the detected defects;

14 displaying the classified defects on a screen,

15                   wherein the step of detecting said defects comprises the substeps of:  
16                   correcting mis-registrations between the plurality of external appearance images  
17 of the inspection subject region and the plurality of external appearance images of the  
18 comparison subject region; and  
19                   detecting defects by comparing the plurality of external appearance images of the  
20 inspection subject region and the plurality of external appearance images of the comparison  
21 subject region corrected in the mis-registrations~~The defect inspection method according to claim~~  
22 14, wherein the step of correcting the mis-registrations comprises the substeps of:  
23                   mixing two perspective images obtained by picking up an image of the inspection  
24 subject region of said sample from each of two opposed directions with a non-directional  
25 electron image, thereby synthesizing a first mixed image;  
26                   mixing two perspective images obtained by picking up an image of the  
27 comparison subject region of said sample from each of the two opposed directions with a non-  
28 directional electron image, thereby synthesizing a second mixed image;  
29                   comparing the first mixed image with the second mixed image, thereby obtaining  
30 mis-registration quantities respectively between the two perspective images and the non-  
31 directional electron image of the inspection subject region of said sample and the two perspective  
32 images and the non-directional electron image of the comparison subject region; and  
33                   correcting mis-registrations respectively between the two external appearance  
34 images and the non-directional electron image of the inspection subject region of said sample  
35 and the two external appearance images and the non-directional electron image of the  
36 comparison subject region, based on the obtained mis-registration quantities.

16-17. (Canceled)

1                   18.   (Currently amended) A defect inspection method comprising the steps of:  
2                   picking up images of a first region of a sample from a plurality of directions,  
3 thereby obtaining a plurality of external appearance images of the first region;  
4                   picking up images of a second region of said sample from a plurality of  
5 directions, thereby obtaining a plurality of external appearance images of the second region;

6                   correcting mis-registrations between the plurality of external appearance images  
7 of the first region and the plurality of external appearance images of the second region;

8                   detecting defects of said sample by using the plurality of external appearance  
9 images of the first region and the plurality of external appearance images of the second region  
10 corrected in the mis-registrations;

11                   classifying the detected defects; and  
12                   storing information concerning the classified defects~~The defect inspection method~~  
13 ~~according to claim 16~~, wherein the step of correcting the mis-registrations comprises the substeps  
14 of:

15                   mixing two perspective images obtained by picking up an image of the first  
16 region of said sample from each of two opposed directions with the image obtained by picking  
17 up an image from the different direction, thereby synthesizing a first mixed image;

18                   mixing two perspective images obtained by picking up an image of the second  
19 region of said sample from each of two opposed directions with the image obtained by picking  
20 up an image from the different direction, thereby synthesizing a second mixed image;

21                   comparing the first mixed image with the second mixed image, thereby obtaining  
22 mis-registration quantities respectively between the two perspective images and the image  
23 obtained by picking up an image from the different direction of the first region of said sample  
24 and the two perspective images and the image obtained by picking up an image from the  
25 different direction of the second region of said sample; and

26                   correcting mis-registrations respectively between the two perspective images and  
27 the image obtained by picking up an image from the different direction of the first region of said  
28 sample and the two perspective images and the image obtained by picking up an image from the  
29 different direction of the second region, based on the obtained mis-registration quantities.

1                   19.   (Currently amended) A defect inspection method comprising the steps of:  
2                   picking up images of a first region of a sample from a plurality of directions,  
3                   thereby obtaining a plurality of external appearance images of the first region;  
4                   picking up images of a second region of said sample from a plurality of  
5                   directions, thereby obtaining a plurality of external appearance images of the second region;  
6                   correcting mis-registrations between the plurality of external appearance images  
7                   of the first region and the plurality of external appearance images of the second region;  
8                   detecting defects of said sample by using the plurality of external appearance  
9                   images of the first region and the plurality of external appearance images of the second region  
10                  corrected in the mis-registrations;  
11                  classifying the detected defects; and  
12                  storing information concerning the classified defects.  
13                  ~~The defect inspection method~~  
14                  ~~according to claim 16,~~ wherein the step of detecting said defects uses,  
15                  information of a difference image ~~and information of a sum image~~ of two  
16                  perspective images obtained by picking up an image of the first region of said sample from each  
17                  information of a difference image ~~and information of a sum image~~ of two  
18                  perspective images obtained by picking up an image of the second region from each of two  
19                  opposed directions.

20-21. (Canceled)

1                   22.   (Currently amended) A defect inspection method comprising the steps of:  
2                   picking up images of a first region of a sample from a plurality of directions,  
3                   thereby obtaining a plurality of external appearance images of the first region;  
4                   picking up images of a second region of said sample from a plurality of  
5                   directions, thereby obtaining a plurality of external appearance images of the second region;

6 transmitting data of the plurality of external appearance images of the first region  
7 of said sample and data of the plurality of external appearance images of the second region of  
8 said sample;

9 detecting defects of said sample by using the transmitted plurality of external  
10 appearance images of the first region of said sample and the transmitted plurality of external  
11 appearance images of the second region of said sample; and

12 classifying the detected defects~~The defect inspection method according to claim~~  
13 ~~21~~, wherein the step of detecting said defects uses,

14 information of a difference image ~~and information of a sum image~~ of two  
15 perspective images obtained by picking up an image of the first region of said sample from each  
16 of two opposed directions, and

17 information of a difference image ~~and information of a sum image~~ of two  
18 perspective images obtained by picking up an image of the second region from each of two  
19 opposed directions.

23. (Canceled)

1 24. (New) A defect inspection apparatus comprising:  
2 electron beam irradiation unit for irradiating an inspection target with an  
3 electronic beam focused thereon in a scanning manner;  
4 a detection unit including a pair of narrow angle electron detectors and a non-  
5 directional electron detector, the narrow angle electron detectors detecting in narrow angle  
6 directions which are different from each other, electrons generated from the inspection target  
7 which is irradiated with the electron beam focused by the electron beam irradiation unit;  
8 an imaging unit for imaging a pair of detection signals detected by the pair of  
9 narrow angle electron detectors of the detection unit to produce a pair of perspective images, and  
10 for imaging a detection signal detected by the non-directional electron detector to produce a  
11 secondary electron image; and  
12 an image processing unit for processing respective images of a defect portion and  
13 a reference portion of the inspection target which are imaged through the imaging unit by

14 detecting the defect portion and the reference portion through the detection unit so as to detect a  
15 defect position of the inspection target;

16 wherein the image processing unit calculates a difference image of each of the  
17 pair of perspective images of the respective defect and reference portions, and detects the defect  
18 position of the inspection target from the calculated respective difference images between the  
19 defect and reference portions.

1 25. (New) A defect inspection apparatus according to Claim 24 wherein the  
2 image processing unit calculates a difference image concerning the calculated respective  
3 difference images between the defect and reference portions, calculates a difference image  
4 between the calculated difference image of the defect portion and the calculated difference image  
5 of the reference portion, calculates a difference image of the secondary electron image between  
6 the defect portion and the reference portion, and detects the defect position of the inspection  
7 target from the calculated difference image between the defect portion and reference portion and  
8 the calculated difference image of the secondary electron image between the defect portion and  
9 the reference portion.

1 26. (New) A defect inspection apparatus comprising:  
2 an electron beam irradiation unit for irradiating an inspection target with an  
3 electronic beam focused thereon in a scanning manner;  
4 a detection unit including a pair of narrow angle electron detectors and a non-  
5 directional electron detector, the narrow angle electron detectors detecting in narrow angle  
6 directions which are different from each other, electrons generated from the inspection target  
7 which is irradiated with the electron beam focused by the electron beam irradiation unit;  
8 an imaging unit for imaging a pair of detection signals detected by the pair of  
9 narrow angle electron detectors of the detection unit to produce a pair of perspective images, and  
10 for imaging a detection signal detected by the non-directional electron detector to produce a  
11 secondary image;  
12 a three-dimensional shape image calculation unit for calculating from the pair of  
13 perspective images and the secondary image which are imaged by the imaging unit, a three-

14 dimensional shape of a part or a whole region of these images to produce a three-dimensional  
15 shape image; and  
16 an image processing unit for processing the three-dimensional shape image of a  
17 defect portion and a reference portion of the inspection target, which is produced from the three-  
18 dimensional shape image calculation unit by detecting the defect portion and the reference  
19 portion through the detection unit and by imaging the defect portion and the reference portion so  
20 as to detect a defect position of the inspection target.